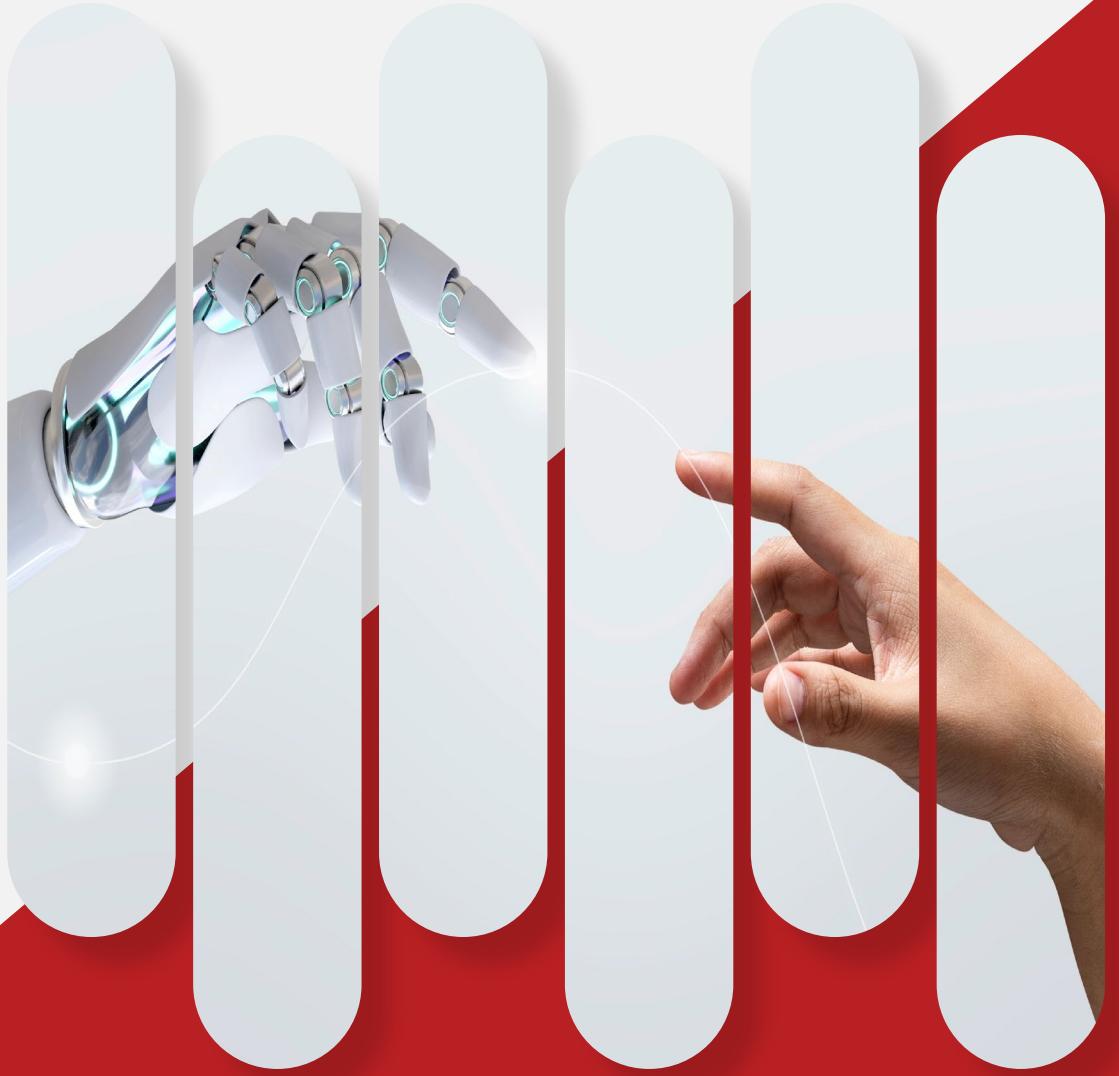


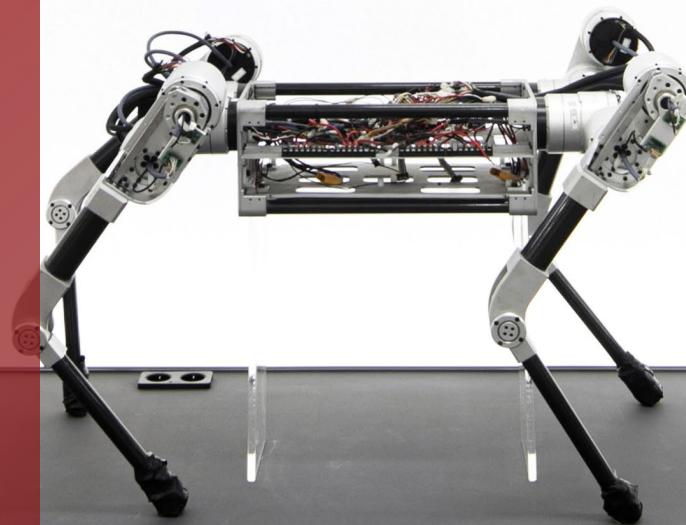
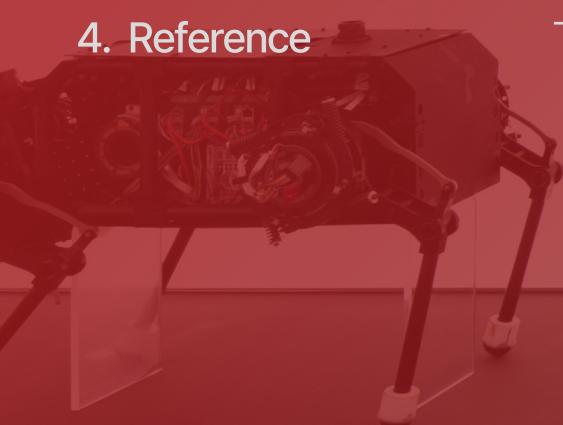
AIDIN ROBOTICS

**Physical Interaction Intelligence
for Humanoid and Cobot**



Index

- 1. Company Overview ----- 3 - 9
- 2. Core Technologies ----- 10 - 16
- 3. Product Portfolio ----- 17 - 31
- 4. Reference ----- 32 - 35



01. Company Overview

Physical Interaction Intelligence
for Humanoid and Cobot

AIDIN ROBOTICS



Company Overview



Name AIDIN ROBOTICS Inc.



CEO HyoukRyeol Choi, YoongHaeng Lee



Business
Robot Components Business
(F/T Sensors, Grippers, Hands, Safety Sensors, etc.)
Robotic Application Solutions Business
(Collaborative Robots, Quadruped Robots, Humanoids)



Found Date Nov 21, 2019



Number of Employee 54 [Ph.D 10 members]



Address
Head : 5F, 12-20, Simin Daero 327beon gil, Anyang, Dongan-gu,
Gyeonggi-do, South Korea
Labs : 4F, 12-20, Simin Daero 327beon gil, Anyang, Dongan-gu, Gyeonggi-
do, South Korea

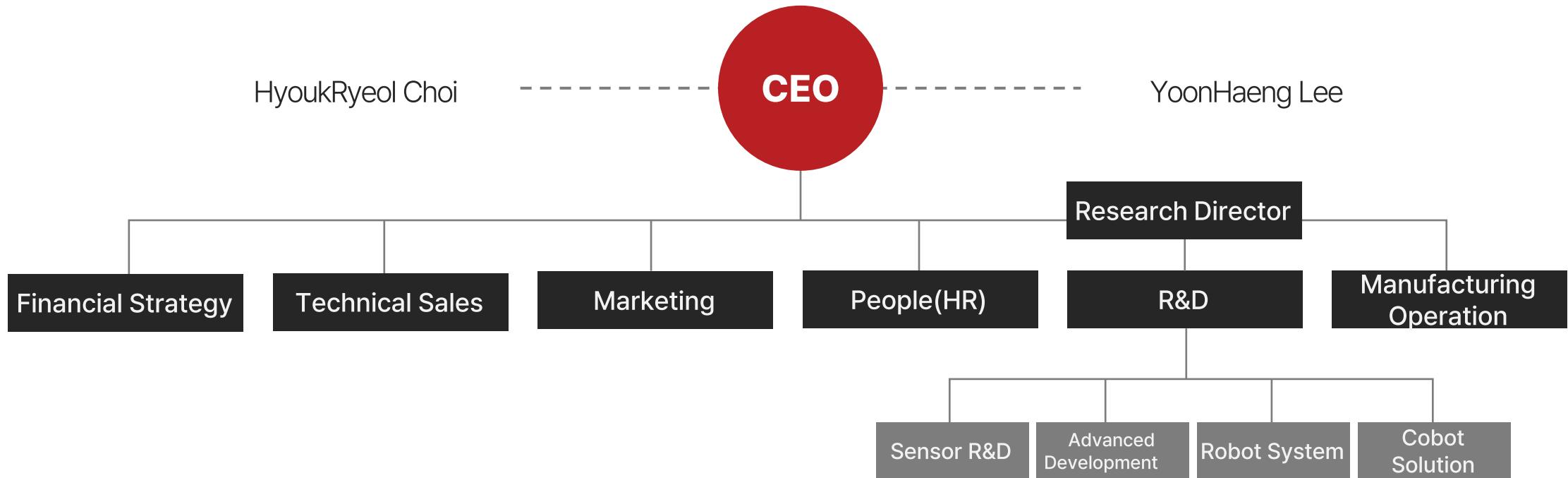


Homepage www.aidinrobotics.co.kr

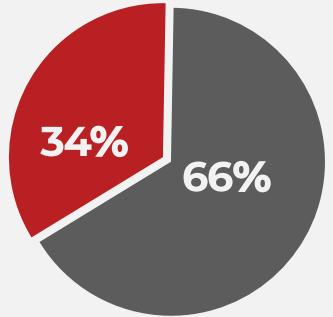
History

2019	Established corporation	✓ Selected in Gyeonggi-do Robot Startup Support Program ✓ Established a Company Research Institute ✓ Selected for Early Startup Package Project ✓ Selected for TIPS Program by the Small & Medium Business Administration	✓ Selected as Core-Tech Development Business in Robotics field (Task Scale 3 billion)	✓ Attraction of investment Series A (KRW 4.5 billion Scale) ✓ Selected as Managing department developing the customized torque sensor for service robot
2020				
2021				
2022				
2023	✓ Selected as Deeptech Incubator for startup 1000+ ✓ Contract for developing quadruped robot with POSCO ✓ Certification of Quality Management System ISO9001:2015	✓ Secured KRW 15 billion Series B investment ✓ Focused on advanced robot operation and gripping performance (in collaboration with KETI and NIST) ✓ Joined the AI Autonomous Manufacturing Alliance under the Ministry of Trade, Industry and Energy ✓ Signed an MOU with CJ Logistics to develop a AIRO One solution for logistics ✓ Selected as Korea's Robot Company of the Year for five consecutive years (as of 2024) ✓ Acquired ISO 45001:2018 Occupational Health & Safety Management System certification	✓ Selected as a C-Lab Outside company to foster ventures and startups by Samsung Electronics ✓ Joined the K-Humanoid Alliance under the Ministry of Trade, Industry and Energy ✓ Designated as a Specialized Company for the AI Factory Project by the same ministry ✓ Leading R&D partner for the Korea ARPA-H 2025 Humanoid Surgical Robot Project ✓ Official member of the Manufacturing M.A.X Alliance (Ministry of Trade, Industry and Energy) ✓ Government-selected project: K-Logistics Humanoid with Robot Hand (CJ Logistics) ✓ Sensors exported to 14 countries worldwide	
2024				
2025				

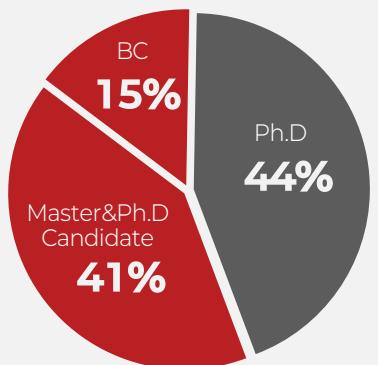
Company Map



Core Member



66% of our team consists of R&D personnel.



85% of our researchers hold master's or doctoral degrees in AI and robotics



HyoukRyeol Choi
President, CEO

- Mechanical Engineering Professor, Sungkyunkwan University
- POSTECH / KAIST / Seoul National University
- IEEE Fellow / Korean Academy of Engineering Member
- 162 Patents



YoonHaeng Lee
CEO

- Ph.D. in Mechanical Engineering, Sungkyunkwan University
- 1st Place, Ministry of Defense Drone Bot Challenge (2019)
- Quadruped Robot System Developer
- Chair, K-Humanoid Alliance

Core Member

Director of Sensor Core Technology



YongBum Kim, CTO

- Ritsumeikan University, Major in Robotics
- Best Award in Mechanical Engineering, 2016 (2016)
- Samsung HumanTech Paper Gold Award, 2016



HyunYong Lee

- Sungkyunkwan University, Ph.D. Program
- Samsung HumanTech Paper Bronze Award, 2012
- KSAE Technology Idea Gold Award, 2013



HoSang Jung, Ph.D

- Sungkyunkwan University, Ph.D. Program
- ICRA RGMC competition Runner-up (2024)



DaWoon Jung, Ph.D

- Korea University, Ph.D Program
- Nature Eletctoronics Research Highlight (2022)



DongYeop Seok, Ph.D

- Sungkyunkwan University, Ph.D. Program
- Samsung HumanTech Paper Gold Award(2016)



JungMin Jeon Ph.D

- Sungkyunkwan University, Ph.D. Program
- Task-Motion Planning System for Socially Viable Service Robots Based on Object Manipulation



Yisac Rhee, Ph.D

- Sungkyunkwan University, Ph.D. Program



KiHyun Kim, Ph.D

- Sungkyunkwan University, Ph.D. Program
- 14 Papers in Soft Robotics, 13 Patents

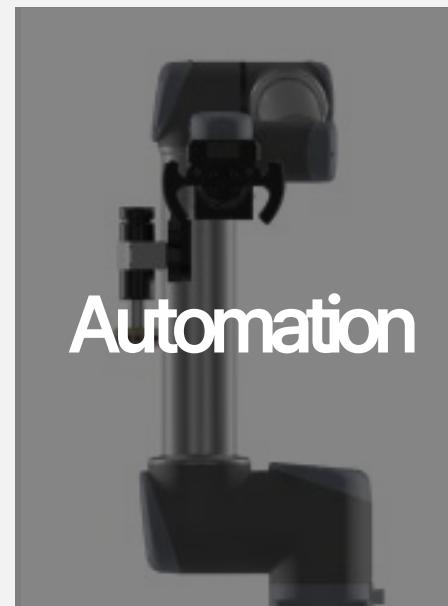
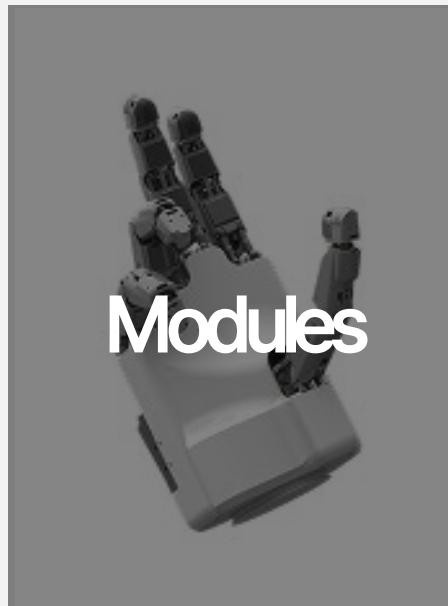
02. Core Technologies

An introduction to AIDIN ROBOTICS' business domains and core technologies.

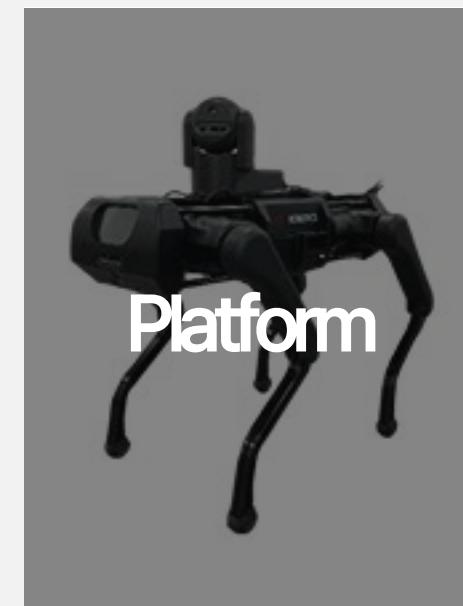
AIDIN ROBOTICS



Business Areas



Physical *Interaction* Intelligence

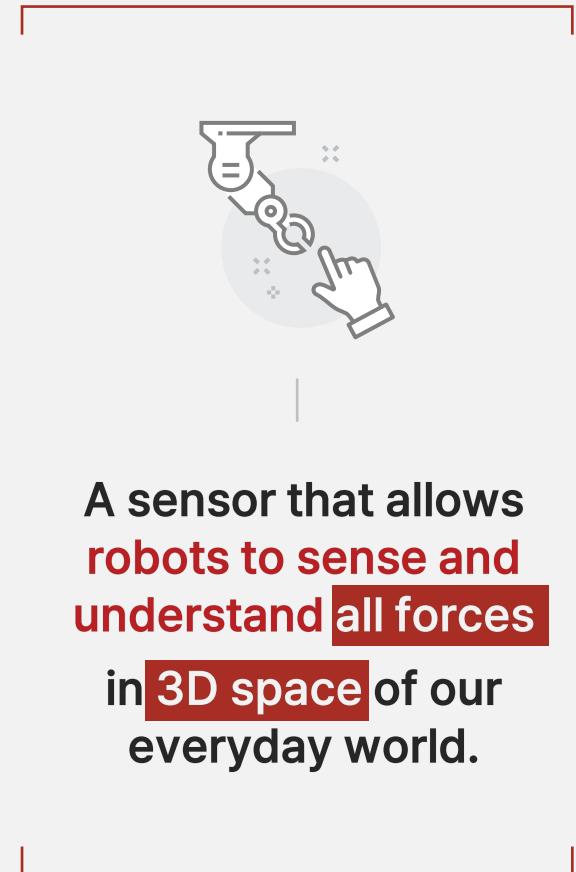
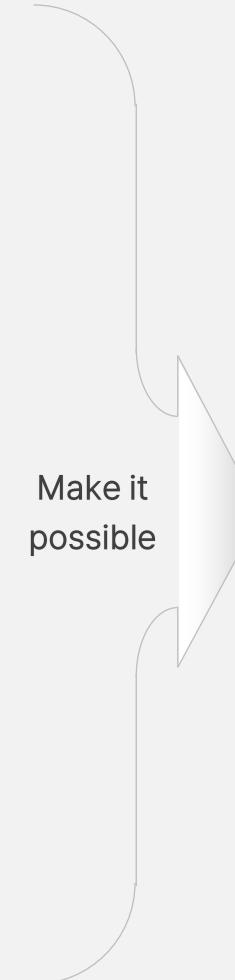
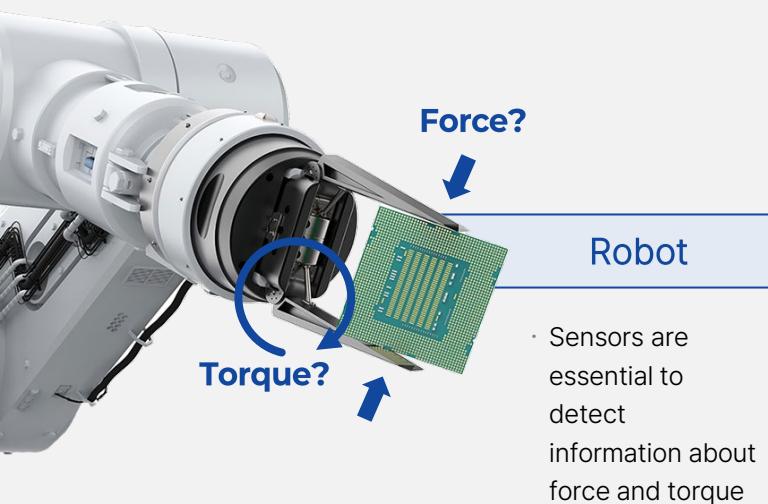


- ✓ Sensors for Co-bot
(6-axis F/T Sensor, Joint Torque Sensor, Co-bot KIT)
- ✓ Sensors for Humanoid Robot
(Fingertip Force Sensor, Tactile Sensor, Wrist Sensor, Ankle Sensor)
- ✓ Force Sensors for Automation Equipment (Sensors/Components for Automation Equipment)
- ✓ Robotic Hand
- ✓ Smart Gripper

- ✓ AIRO-One Polishing Solution
- ✓ AIRO-One Logistic Picking Solution
(Under development)

- ✓ Quadruped Robot (Under Development)

Empowering Robots with a Sense of Touch



A sensor that allows robots to sense and understand all forces in the 3D space of our everyday world.

Core Competencies of AIDIN Sensors



AIDIN ROBOTICS' independently developed world's smallest Miniature 6-axis F/T sensor (AFT20)

High Scalability & Cost Efficiency

Suitable for mass production, offering a unit price about one-tenth of conventional strain gauge sensors, greatly improving cost competitiveness.

Compact & Lightweight

Its miniaturized design allows flexible installation and operation on a variety of robots.

Temperature Compensation

Equipped with built-in temperature compensation, the sensor maintains high accuracy even in real-world environments.

Non-Contact Design

Provides high durability and stability over time due to the absence of mechanical wear.

No Additional Devices Required

Outputs high-precision digital data without the need for separate analog amplifiers or circuits.

AIDIN ROBOTICS Sensor Lineup for Cobot

6-axis F/T Sensor



Basic Type
(AFT200)



Cobot KIT
(AFT200-KIT)

Joint Torque Sensor



50Nm / 100Nm / 200Nm / 400Nm
(Customizable Range)

Embedded
(Custom Type)

Module

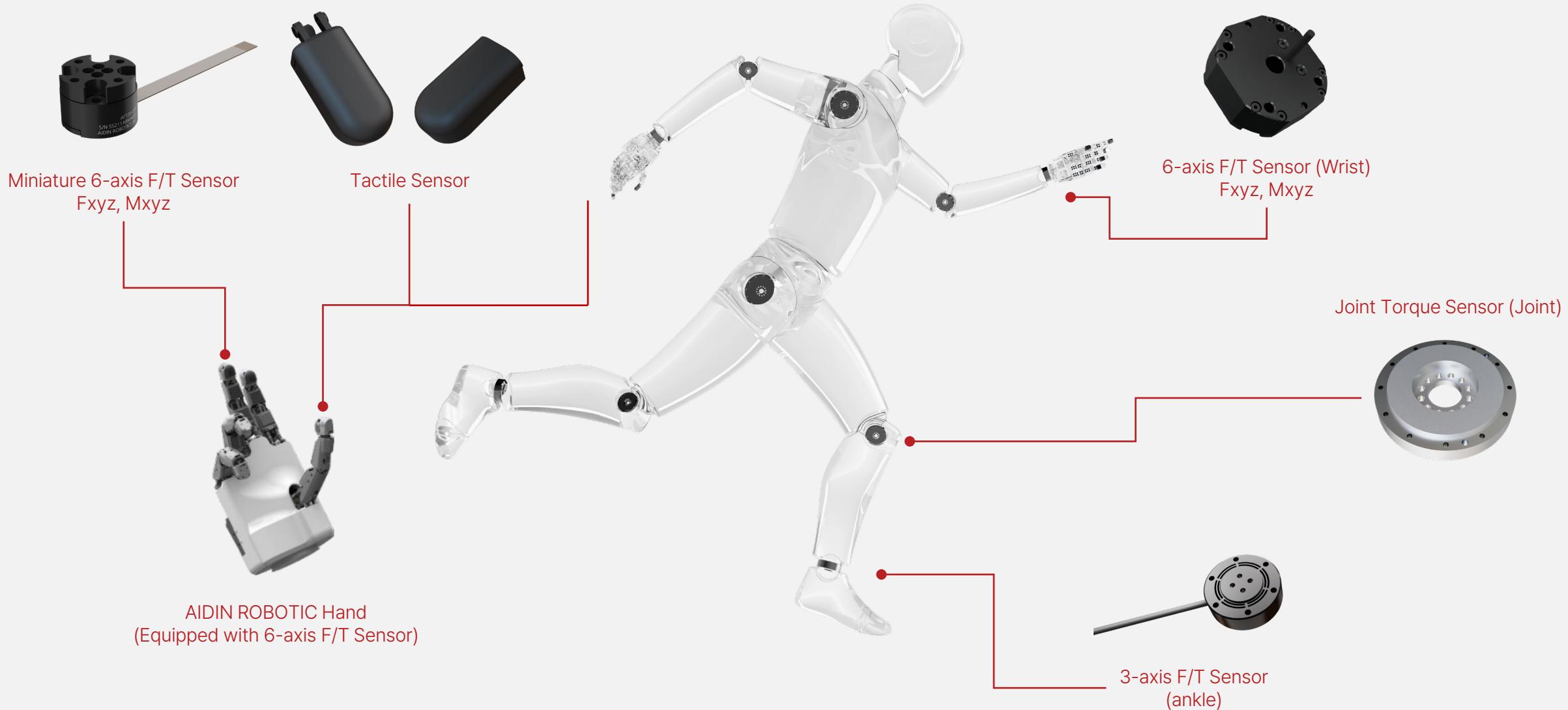


Smart Gripper
(Equipped with 6-axis
F/T Sensor)

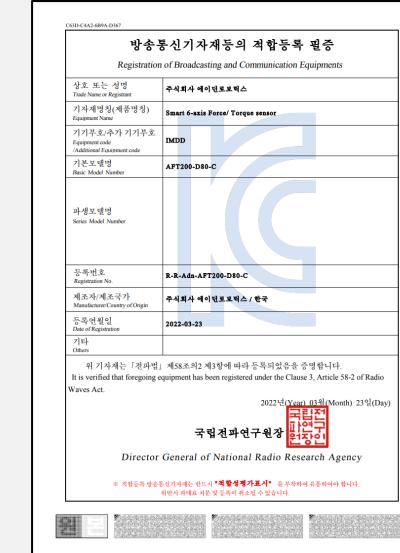
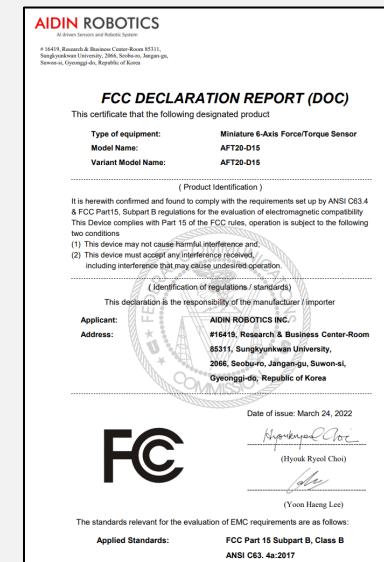
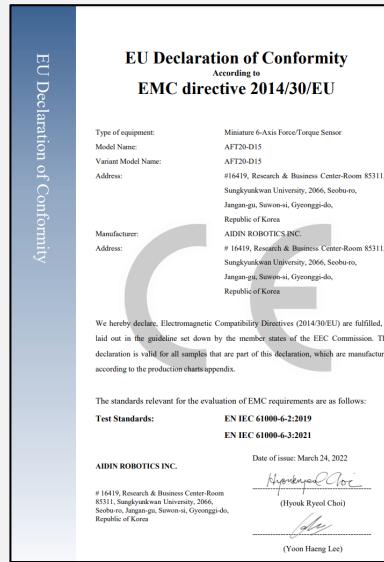
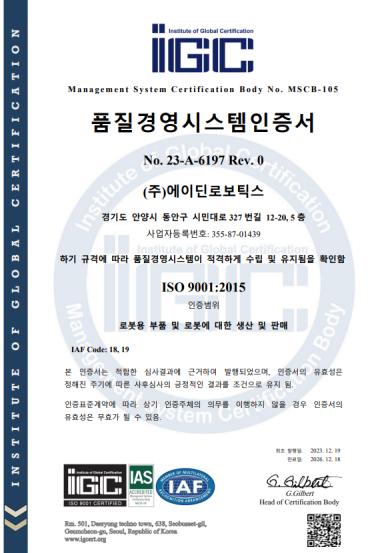


Robot Hand
(Equipped with 6-axis
F/T Sensor)

AIDIN ROBOTICS Sensor Lineup for Humanoid Robot



Certificate



- Differentiated force-sensing technology validated through numerous domestic and international certifications and patents
- Sensor products certified with KC, CE, FCC, and RoHS
- Expanded and fully equipped in-house production facility of over 300 pyeong, certified with ISO 9001 and ISO 45001
- Capable of producing up to 10,000 sensors annually

03. Product Portfolio

Discover the AIDIN product lineup featuring cutting-edge sensing technology.

AIDIN ROBOTICS



Joint Torque Sensor(ATSB)



Used to achieve precise torque measurement and collision detection in robot joints



Index	Unit	Value				
		ATSB 50	ATSB 100	ATSB 200	ATSB 400	
Nominal Torque Range($T\text{N}$)	Nm	50	100	200	400	
Resolution	Nm	0.03	0.05	0.1	0.2	
Interfaces	-	CAN (2.0 A/B)				



3-axis F/T sensor (3FT-1000/2000)



Supports stable walking by measuring foot load and posture in humanoid robots



Index	Unit	3FT 1000	3FT 2000
Nominal Force Range	N	1000	2000
Nominal Torque Range	Nm	20	100
Interfaces	-		CAN

#Humanoid

- ✓ Measures forces and torsion on three axes (Fz, Mx, My) when mounted on a humanoid robot's ankle
- ✓ Accurately measures foot load and posture to enable stable walking
- ✓ Compact design with up to 2000N force measurement → Suitable for humanoid robot joints, ankles, and more



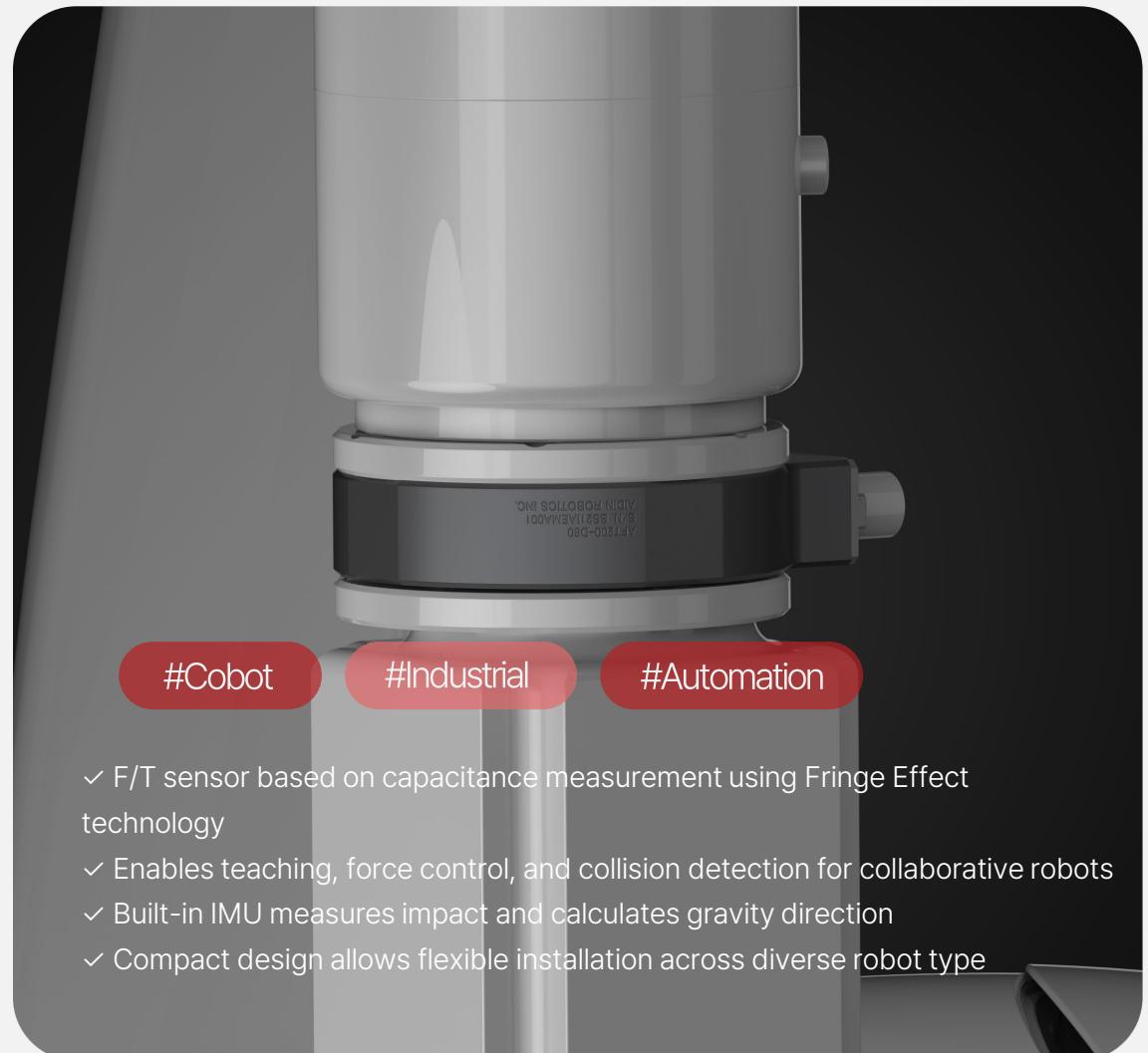
6-axis F/T Sensor(AFT200)



F/T sensor combining capacitance measurement
with Fringe Effect technology



Index	Unit	Value		
		C(CAN)	EN(EtherNET)	EC(EtherCAT)
Nominal Force Range	N		200	
Nominal Torque Range	Nm		15	
Operating Temperature	-	10-50°C		



Miniature 6-axis F/T Sensor (AFT20/50/100)



The World's Smallest 6-axis F/T Sensor

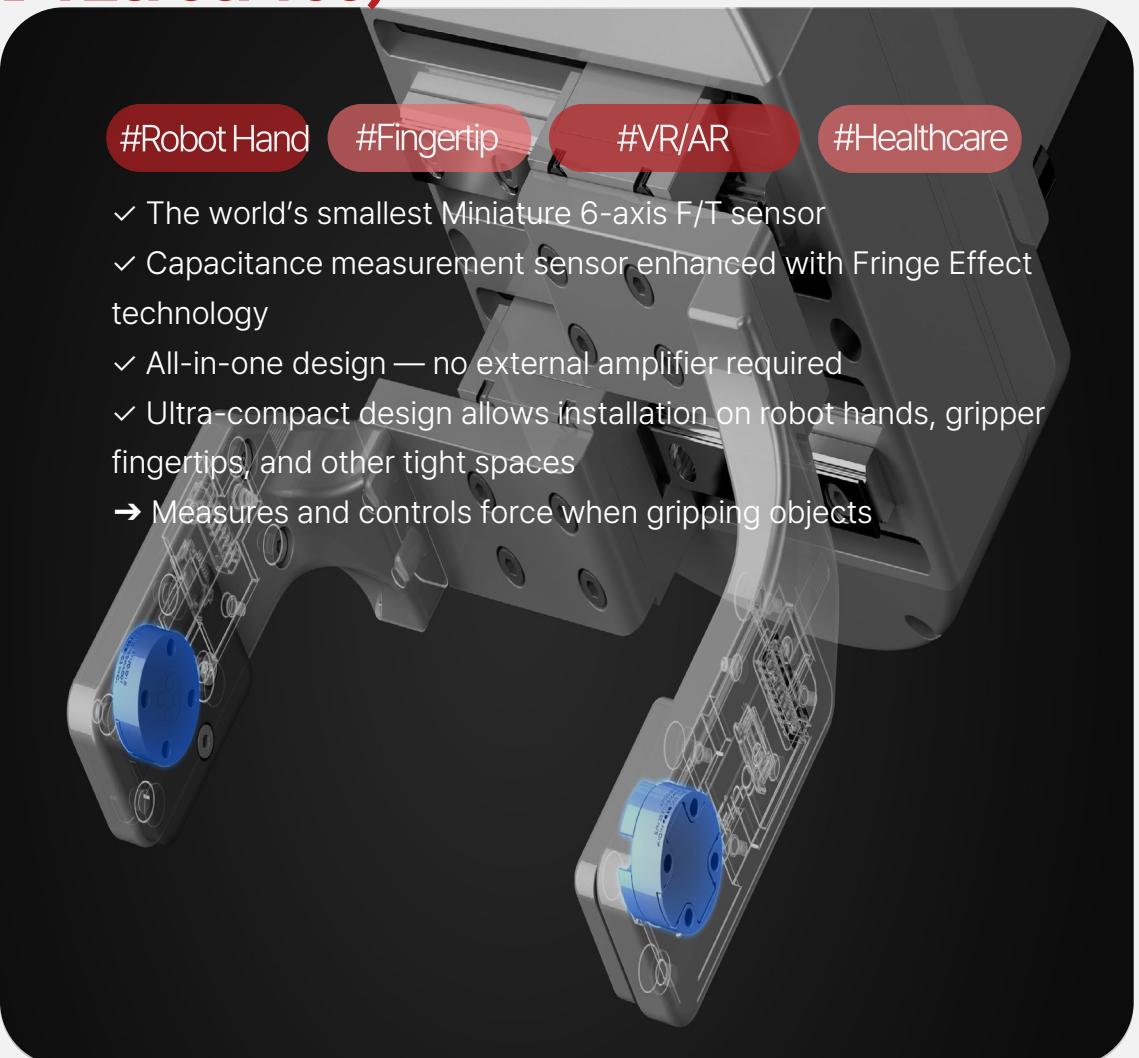


20N/50N

100N



Index	Unit	AFT20-D15	AFT50-D15	AFT100-D20
Force Range	N	20	50	100
Torque Range	Nm	0.1	0.25	0.75
Force Resolution	N	0.05	0.1	0.13
Torque Resolution	Nm	0.0005	0.001	0.002



#Robot Hand

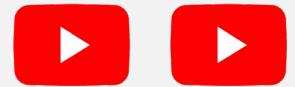
#Fingertip

#VR/AR

#Healthcare

- ✓ The world's smallest Miniature 6-axis F/T sensor
- ✓ Capacitance measurement sensor enhanced with Fringe Effect technology
- ✓ All-in-one design — no external amplifier required
- ✓ Ultra-compact design allows installation on robot hands, gripper fingertips, and other tight spaces
- ➔ Measures and controls force when gripping objects

6-axis F/T Sensor KIT(AFT200-KIT)



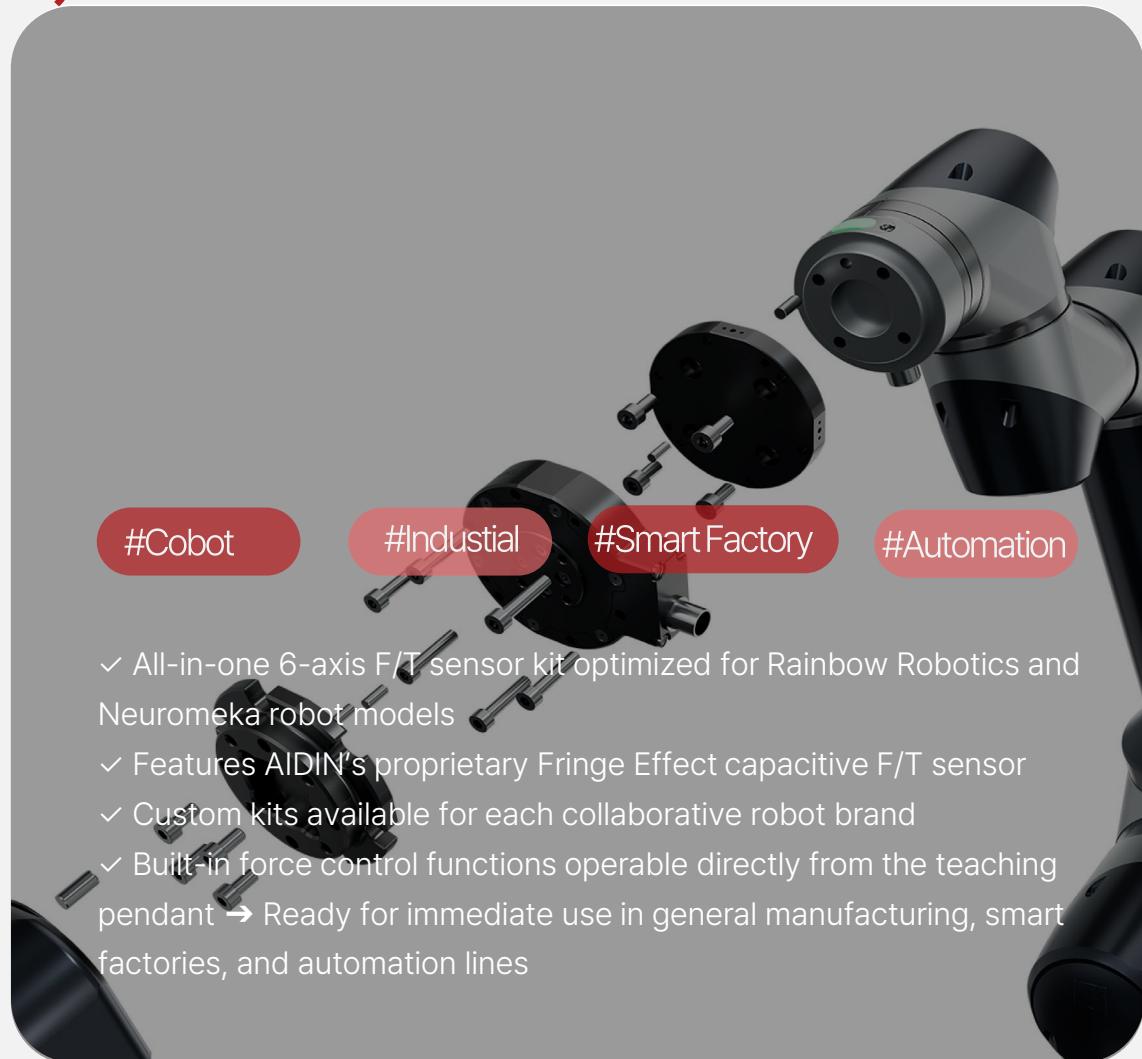
Custom Plug-and-Play Sensor Kits for Collaborative Robot Brand



RAINBOW
ROBOTICS

neuromeka

Index	Unit	AFT200-KIT-RB c (CAN) AFT200-KIT-NRMK c (CAN)
Nominal Force Range	N	200
Nominal Torque Range	Nm	15
Resolution(Fxyz)	N	0.15
Resolution(Txyz)	Nm	0.015

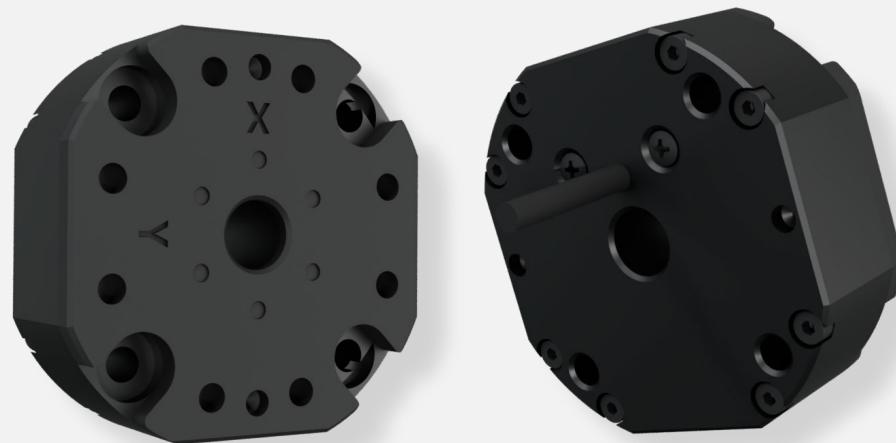


- ✓ All-in-one 6-axis F/T sensor kit optimized for Rainbow Robotics and Neuromeka robot models
- ✓ Features AIDIN's proprietary Fringe Effect capacitive F/T sensor
- ✓ Custom kits available for each collaborative robot brand
- ✓ Built-in force control functions operable directly from the teaching pendant → Ready for immediate use in general manufacturing, smart factories, and automation lines

6-axis F/T Sensor(AFT150-D50)



Mountable on robot wrists and joints to precisely measure multi-axis forces and torques during operations



Index	Unit	Value
Nominal Force Range(F_XYZN)	N	150
Nominal Torque Range(M_XYZN)	Nm	7.5
Interfaces	1,000Kbps	CAN, CAN-FD

#Humanoid #Industrial #Cobot #Gripper

- ✓ Compact hollow-hole design allows easy installation in tight spaces such as robot joints and wrists
- ✓ Supports CAN 2.0 and CAN-FD (select output via commands)
- ✓ All-in-one capacitance sensor — no additional amplifier required

Tactile Sensor(ATT)



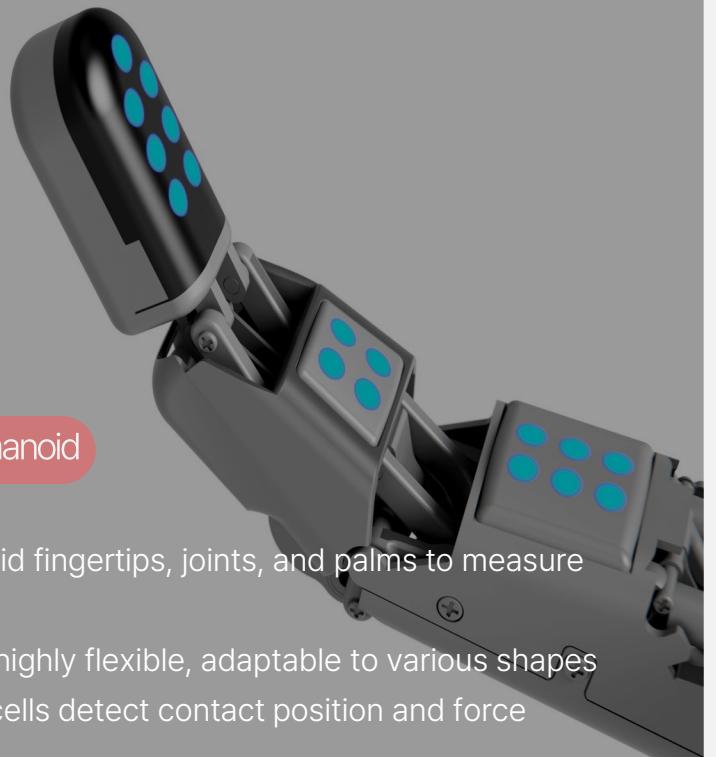
Precisely detects contact pressure and position for delicate robotic touch



Index	Unit	Value
Nominal Force Range	N	30
Force Resolution	mN	6
Interfaces	-	CAN

#Robot Hand #Humanoid

- ✓ Mounted on humanoid fingertips, joints, and palms to measure object contact
- ✓ Polymer-based and highly flexible, adaptable to various shapes
- ✓ Multi-array sensing cells detect contact position and force distribution
- ✓ Enables precise and stable handling of diverse objects



Panoradar Safety Sensor(ARS-5000)



Safety sensor enabling safe human-robot collaboration
(Under Development)



#Cobot

#AGV/AMR

- ✓ Precisely detects surroundings and obstacles for safe operation
- ✓ FMCW radar sensor with ultra-wideband communication
- ✓ 360° blind-spot-free sensing with high accuracy
- ✓ Digital interface (EtherNet)

Robot Motion Controller (ARC)

Controller compatible with F/T sensors, assisting in motion and force control



Index	ARC 6	ARC 11
CPU	6th gen Intel	11th gen Intel
Interfaces	EtherNET, EtherCAT	
Operating System	1. RT-OS Ubuntu 14.04 Xenomai 2.4 2. RT-OS Ubuntu 20.04 Xenomai 3.2.4 (SOEM) (Pick 1)	RT-OS Ubuntu 20.04 Xenomai 3.2.4 (SOEM)



- ✓ Real-time robot motion controller compatible with AIDIN Robotics sensors for motion and force control in collaborative robots
- ✓ Equipped with Xenomai for real-time control
- ✓ Supports high-speed communication via EtherCAT and ROS

Robot Motion Controller (ARC)

Controller compatible with F/T sensors, assisting in motion and force control



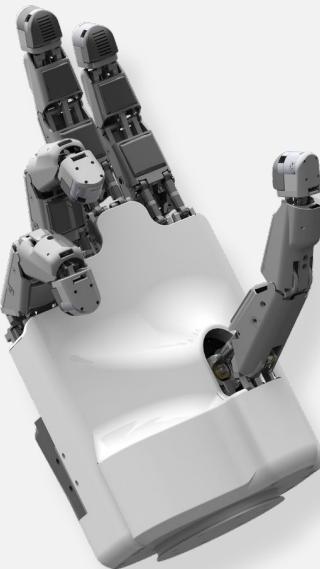
Index	ARC 6	ARC 11
CPU	6th gen Intel	11th gen Intel
Interfaces	EtherNET, EtherCAT	
Operating System	1. RT-OS Ubuntu 14.04 Xenomai 2.4 2. RT-OS Ubuntu 20.04 Xenomai 3.2.4 (SOEM) (Pick 1)	RT-OS Ubuntu 20.04 Xenomai 3.2.4 (SOEM)



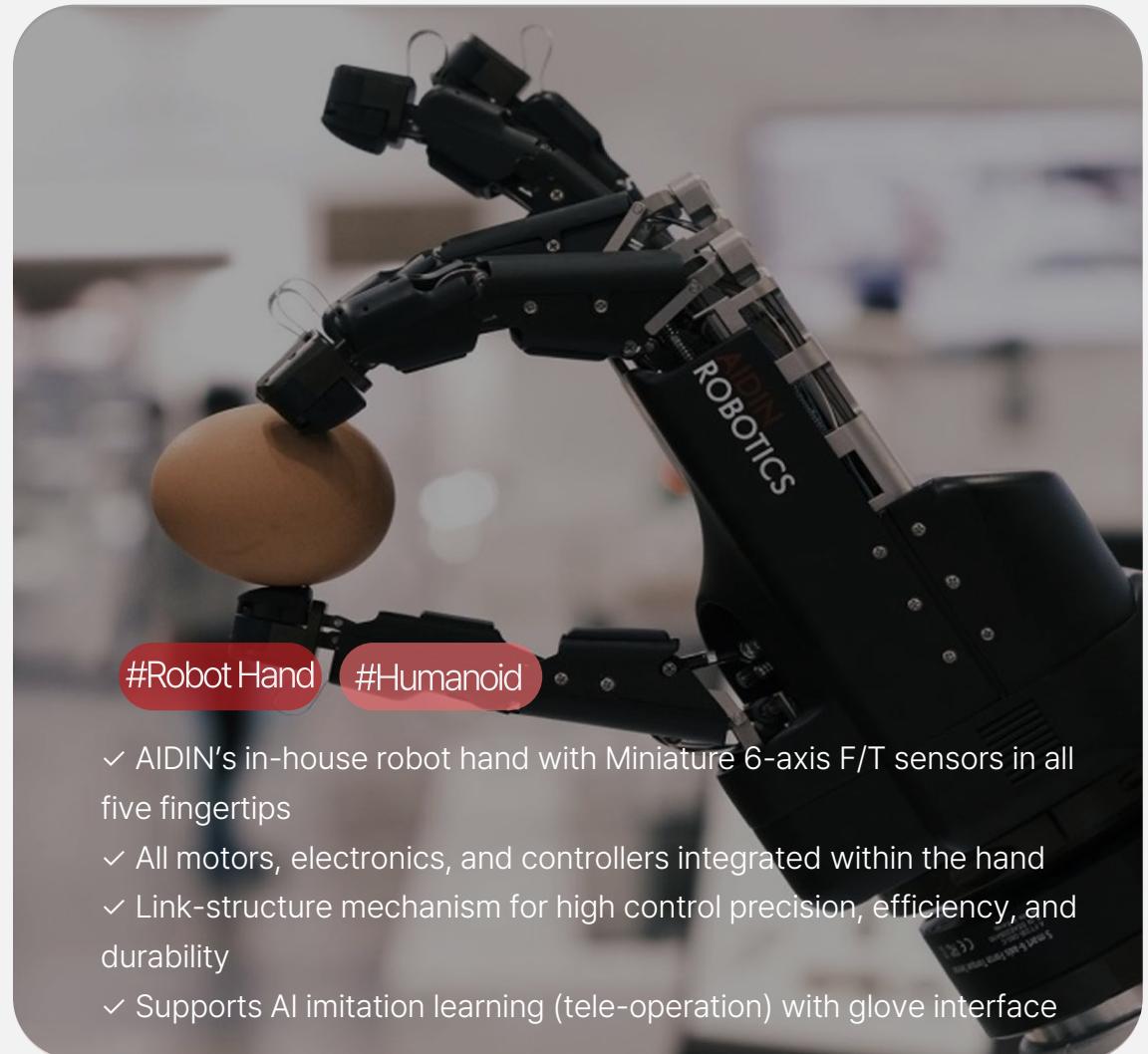
- ✓ Real-time robot motion controller compatible with AIDIN Robotics sensors for motion and force control in collaborative robots
- ✓ Equipped with Xenomai for real-time control
- ✓ Supports high-speed communication via EtherCAT and ROS

Robotic Hand (AIDIN-Hand)

High-degree-of-freedom robot hand
equipped with a 6-axis F/T sensor



Index	Unit	Value
Degree of Freedom(Finger)	DoF	3
Degree of Freedom(Hand)	DoF	15
Finger-tip Force	N	20
Payload	Kg	15



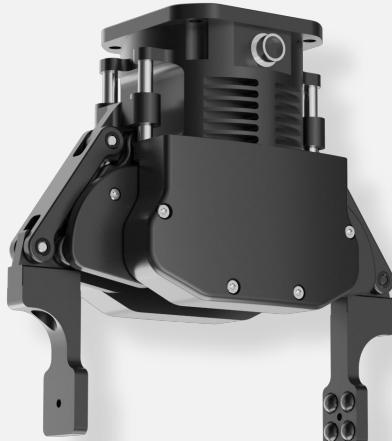
#Robot Hand #Humanoid

- ✓ AIDIN's in-house robot hand with Miniature 6-axis F/T sensors in all five fingertips
- ✓ All motors, electronics, and controllers integrated within the hand
- ✓ Link-structure mechanism for high control precision, efficiency, and durability
- ✓ Supports AI imitation learning (tele-operation) with glove interface

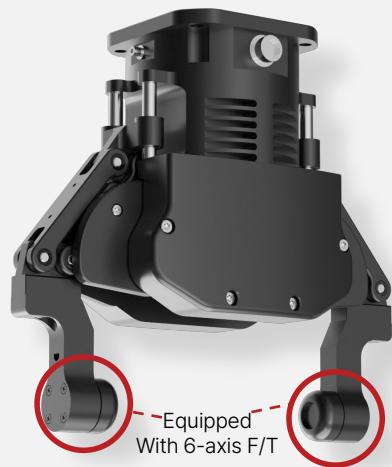
Smart Gripper(SusGrip/SusGrip-FT)



Equipped with wide parallel gripping up to 128mm and fine manipulation capability

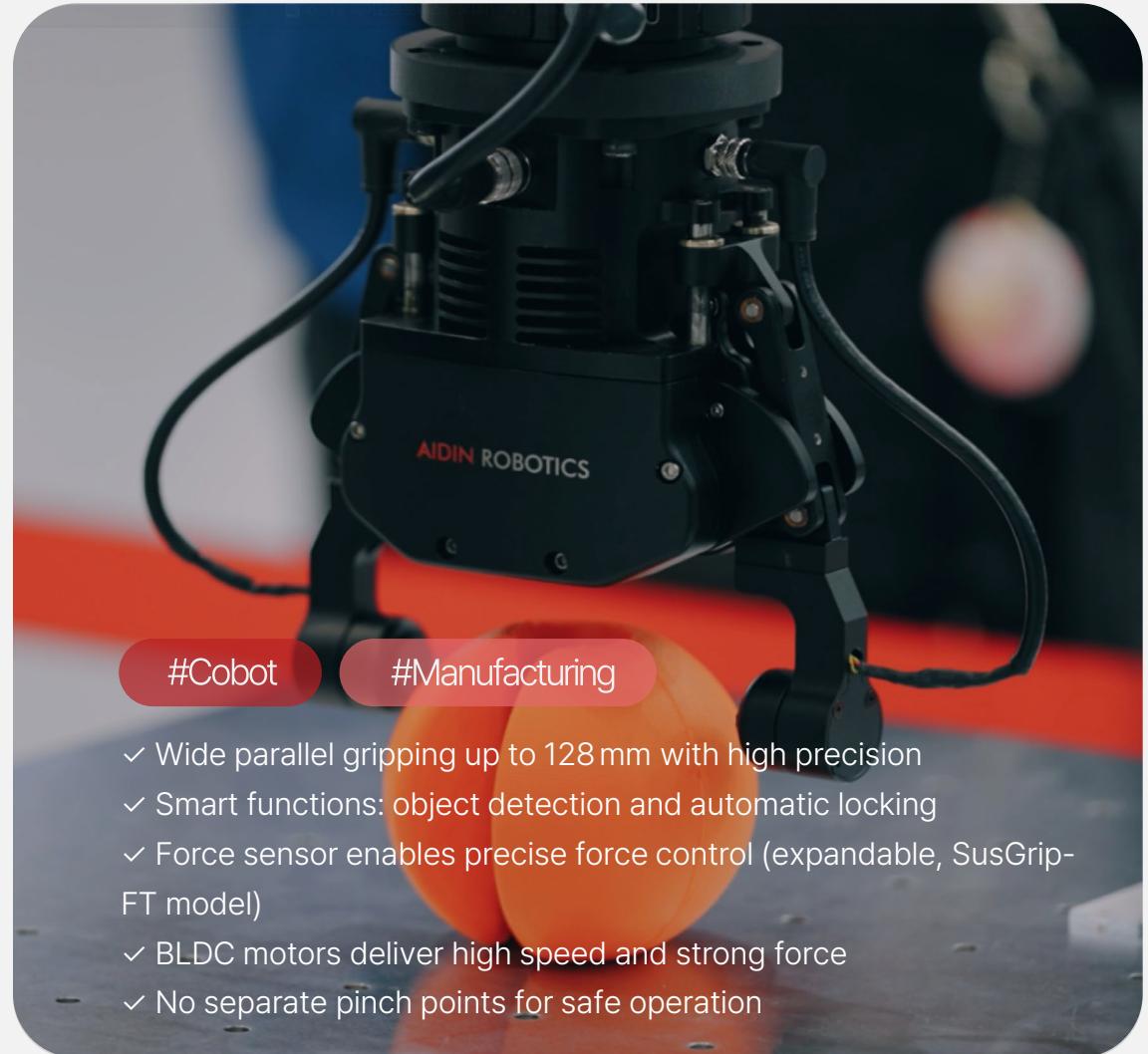


SusGrip



SusGrip-FT

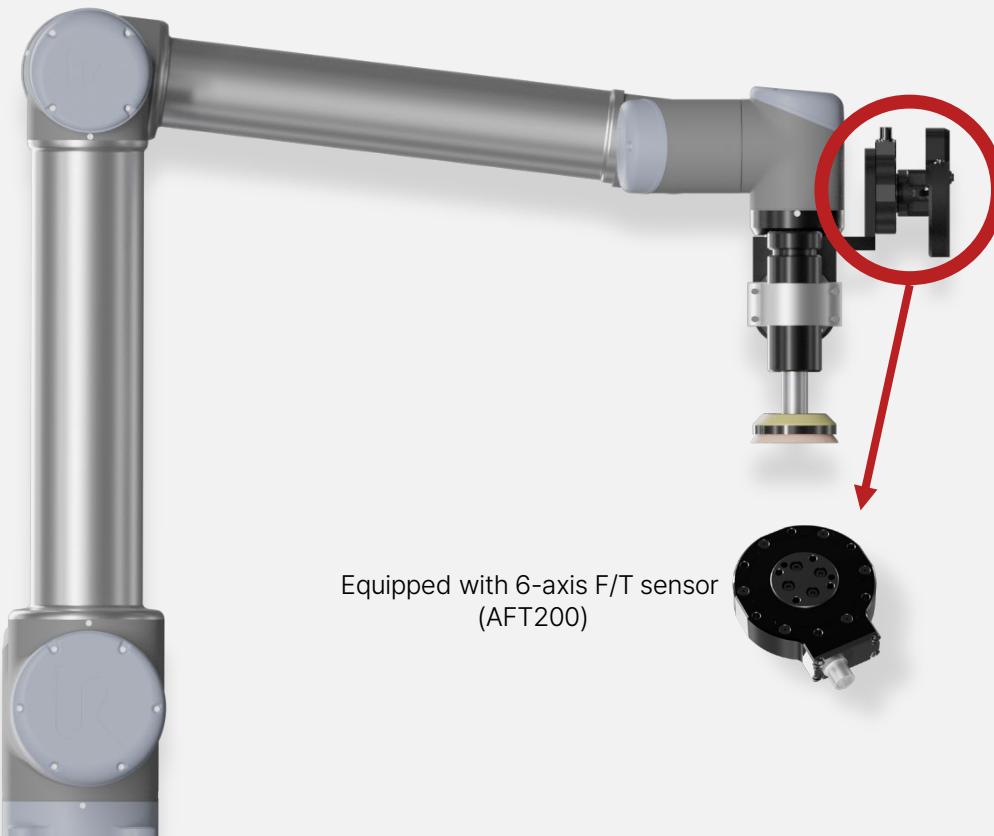
Index	Unit	Value
Gripping Force	N	90
Stroke	mm	0-128
Form-fit Payload	Kg	5



AIRO One Solution – Surface Finishing



Force Control Solution for Manufacturing



Solution Setup



Cobot
(Universal Robot UR 10e)



6-axis F/T Sensor
(AFT200)



Robot Motion
Controller
(ARC)



Customizing Tool

- ✓ $\pm 0.1\text{ N}$ precision sensing/control with 6-axis F/T sensor
- ✓ Up to 16 h continuous operation
- ✓ Independent robot control without extra equipment
- ✓ Intuitive environment for easy programming and fast deployment

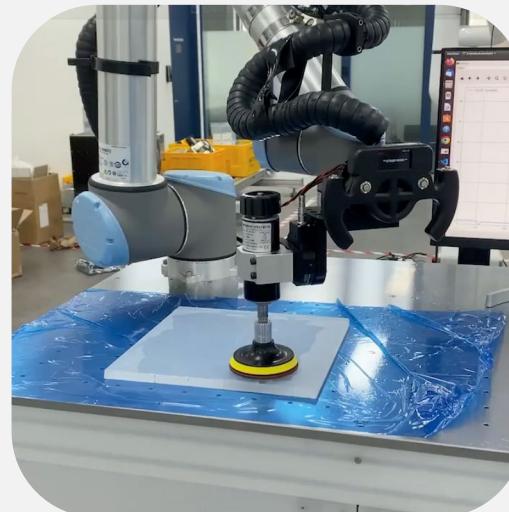
AIRO One Solution – Surface Finishing

Force Control Solution for Manufacturing

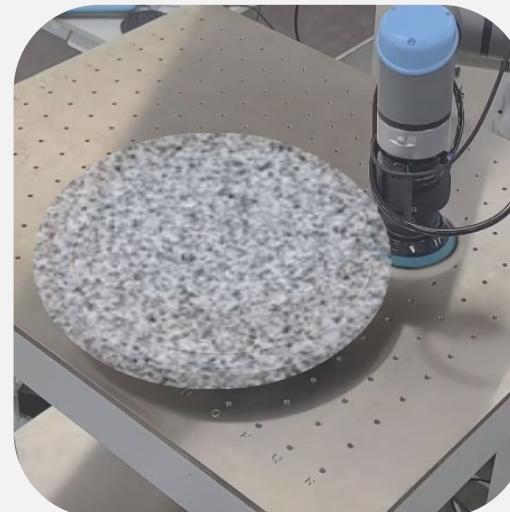
Application Case



✓ Metal surface processing



✓ Quartz surface polishing



✓ Cleaning process

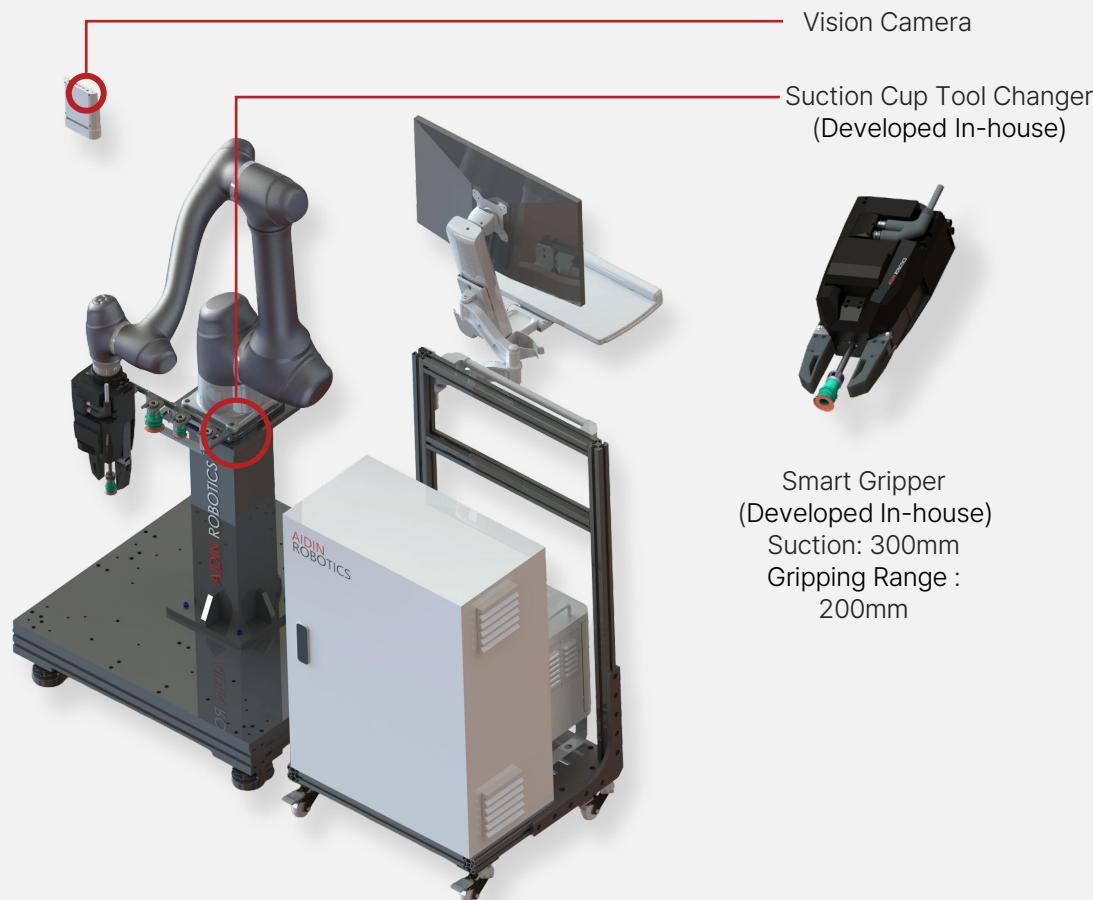


✓ Coating/film removal process

AIRO One Solution – Logistics



Robotic Picking Solution for Logistics
(Under Development)



성능

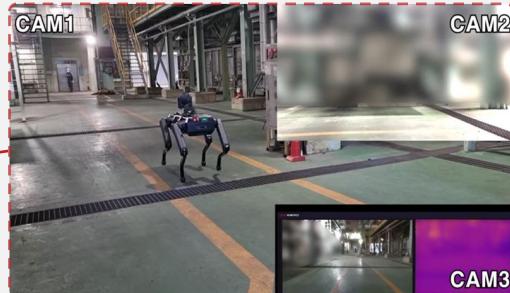
- ✓ Productivity: 1000 pieces per hour
- ✓ Grippable Object Weight : 3kg
- ✓ Maximum Grippable Object Size : 300mm

- ✓ Logistics robot solution that recognizes and grips random objects without pre-registration
- ✓ Integrates in-house AI vision algorithms with a smart gripper capable of handling objects of various types and sizes
- ✓ Unified suction and gripper control for optimal gripping strategy

Quadruped Robot Solution



AIDIN (Under Development, with **posco**)



Quadruped robot (AIDIN) used for thermal imaging and other inspections in hazardous facilities such as power plants and chemical factories

- ✓ Human-like legged (RGB/thermal cameras, surveillance, vibration, gas sensors, etc.) mobility for navigating stairs, slopes, and uneven terrain
- ✓ Enables inspection in hazardous environments such as power plants and chemical plants
- ✓ Modular design allows performance tuning and easy maintenance
- ✓ Supports customized solutions with various attachments

04. Customer Cases

AIDIN ROBOTICS will work with partners to realize the safe coexistence of humans and robots.

AIDIN ROBOTICS



Main Customers



Company



Research



University



TECHNISCHE
UNIVERSITÄT
WIEN



Reference

Manufacturing



Rainbow Robotics



Neuromeka



Healthcare



SAINT LOUIS
UNIVERSITY™



부산대학교
PUSAN NATIONAL UNIVERSITY



AI&Humanoid



ROBROS

ROBOTIS



AIDIN ROBOTICS

Investments

AIDIN ROBOTICS began with seed investment in 2020, successfully raised KRW 4.5 billion in Series A in 2022, and KRW 15 billion in Series B in 2024, surpassing a total cumulative investment of KRW 20 billion.

The company has been continuously growing, recognized for its high potential and value in technology by leading domestic and international corporations.



A faint watermark of the AIDIN ROBOTICS logo is visible in the background, featuring a stylized orange and white geometric design.

“ Thank you

AIDIN ROBOTICS